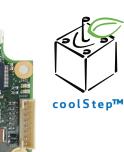


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10 mm

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+

TMCM-1160

1-Axis Motor Mountable 57/6omm | NEMA23/24 Controller / Driver 2.8A / 48V sensOstep™ Encoder Serial Interface

	MAIN CHARACTERISTICS
ELECTRICAL DATA	\cdot 9V to 51V DC supply voltage
	• up to 2.8A RMS coil current
SUPPORTED MOTORS	 two-phase bipolar stepper motors
	• mountable on 57/60mm NEMA23/24 mo-
	tors
INTERFACE	RS485, USB and CAN
	 step&direction interface
	 inputs for ref. & stop switches
	• 4 general purpose I/Os
	 incremental a/b/n encoder interface
FEATURES	• up to 256 times microstepping
	 memory for 2048 TMCL[™] commands
	 stallGuardz[™] sensorless load detection
	• coolStep™ sensorless load dependent cur-
	rent control
	 microPlyer[™] 16 to 256 times microstepping interpolation
	 integrated absolute sensOstep[™] encoder with 1024 pps.
	\cdot automatic ramp generation in hardware
	\cdot on the fly alteration of motion parameters
SOFTWARE	• standalone or remote controlled operation
	 PC-based (Windows) application develop- ment software TMCL-IDE downloadable
	 ready for CANopen
	nluggable IST connectors

- **OTHER** pluggable JST connectors
 - RoHS compliant
 - size: 60 x 60 mm²

ORDER CODE	DESCRIPTION
TMCM-1160	1-axis controller / driver module 2.8A / 48V
Related Products	QMot motors QSH5718 and QSH6018
TMCM-1160-CABLE	Cable loom including all neccessary cables (single ended)

INFO The TMCM-1160 is an intelligent stepper motor controller/driver module featuring the new outstanding coolStep[™] technology for sensorless load dependent current control. This allows energy efficient motor operation. With the advanced stall-Guard2[™] feature the load of the motor can be detected with high resolution. The module is designed to be mounted directly on a 57 or 60mm flange stepper motor. It converts the motor into a compact mechatronic device with serial bus oriented or standalone control.

The **TMCM-1160** is equipped with TRINAMICs **sensOstep™** encoder with 1024 pps and offers an a/b/n encoder interface. The PC based software development environment TMCL-IDE for the Trinamic Motion Control Language **TMCL™** can be downloaded free of charge from the TRINAMIC website. Predefined high level TMCL commands guarantee a rapid development of motion control applications. Communication traffic is kept very low since all time critical operations, e.g. ramp calculation are performed onboard.

