+





+

TMCM-1021

1-Axis Motor Mountable 28mm | NEMA11 Controller / Driver 0.7A / 24V RS485 Interface

	MAIN CHARACTERISTICS
ELECTRICAL DATA	• 24 V DC (nom.) supply voltage
	• up to 0.7A RMS coil current
SUPPORTED	 two-phase bipolar stepper motors
MOTORS	• mountable on QMot motors (28mm/ NEMA11)
INTERFACE	• RS485
	 step&direction interface
	 inputs for ref. & stop switches
	• general purpose I/Os
FEATURES	• up to 256 times microstepping
	 memory for 876 TMCL[™] commands
	 stallGuardz[™] sensorless load detection
	 coolStep[™] sensorless load dependent cur- rent control
	 microPlyer[™] 16 to 256 times microstepping interpolation

- integrated absolute sensOstep[™] encoder with 1024 pps.
- · automatic ramp generation in hardware
- on the fly alteration of motion parameters
- SOFTWARE standalone or remote controlled operation
 - PC-based (Windows) application development software TMCL-IDE downloadable
 - **OTHER** pluggable JST connectors
 - · RoHS compliant
 - size: 28 x 28 mm²

ORDER CODE	DESCRIPTION
TMCM-1021	1-axis controller / driver module 0.7A / 24V
TMCM-1021-CABLE	Cable loom including all neccessary cables (single ended)
Related products:	QMot motor QSH2818

module featuring the new outstanding coolStep[™] technology for sensorless load dependent current control. This allows energy efficient motor operation. With the advanced stallGuardz[™] feature the load of the motor can be detected with high resolution. The module is designed to be mounted directly on a 28mm flange QMot stepper motor. It converts the motor into a compact mechatronic device with serial bus oriented or standalone control. The PC based software development environment TMCL-IDE for

INFO The TMCM-1021 is an intelligent stepper motor controller/driver

the Trinamic Motion Control Language (TMCL™) can be downloaded free of charge from the TRINAMIC website. Predefined high level TMCL commands guarantee a rapid development of motion control applications. Communication traffic is kept very low since all time critical operations, e.g. ramp calculation are performed onboard.

